

# Survey Innovations

**1<sup>st</sup> FIG Young Surveyors  
European Meeting (Lisbon)**

**DRAVOSA Survey Department  
17-18 october 2013**



**Van Oord**



# PUMA Survey Innovations



**VanOord Survey Department**  
**17 october 2013**

# PUMA Organization



- Boskalis 50%
- Van Oord 50%



**Koninklijke  
Boskalis Westminster nv**

**Van Oord**



# Port investments Rotterdam

- MV2 2,9 billion (total till 2030)  
including connection with MV1,  
including PUMA
- Contract PUMA 1,1 billion (Construction 1st fase)  
including 200 million BAVO-MV2



# Final Phase - 2030



# Maasvlakte 2 in 2030



**December 2008**



January 2010



January 2011



February 2012



February 2012



July 2012



# Contract 1

## Seawall Defence and Port Reclamation (Phase 1)

Hard Seawall Defence 3.5 km

Beach and dunes 7.3 km

Harbour basins 530 ha

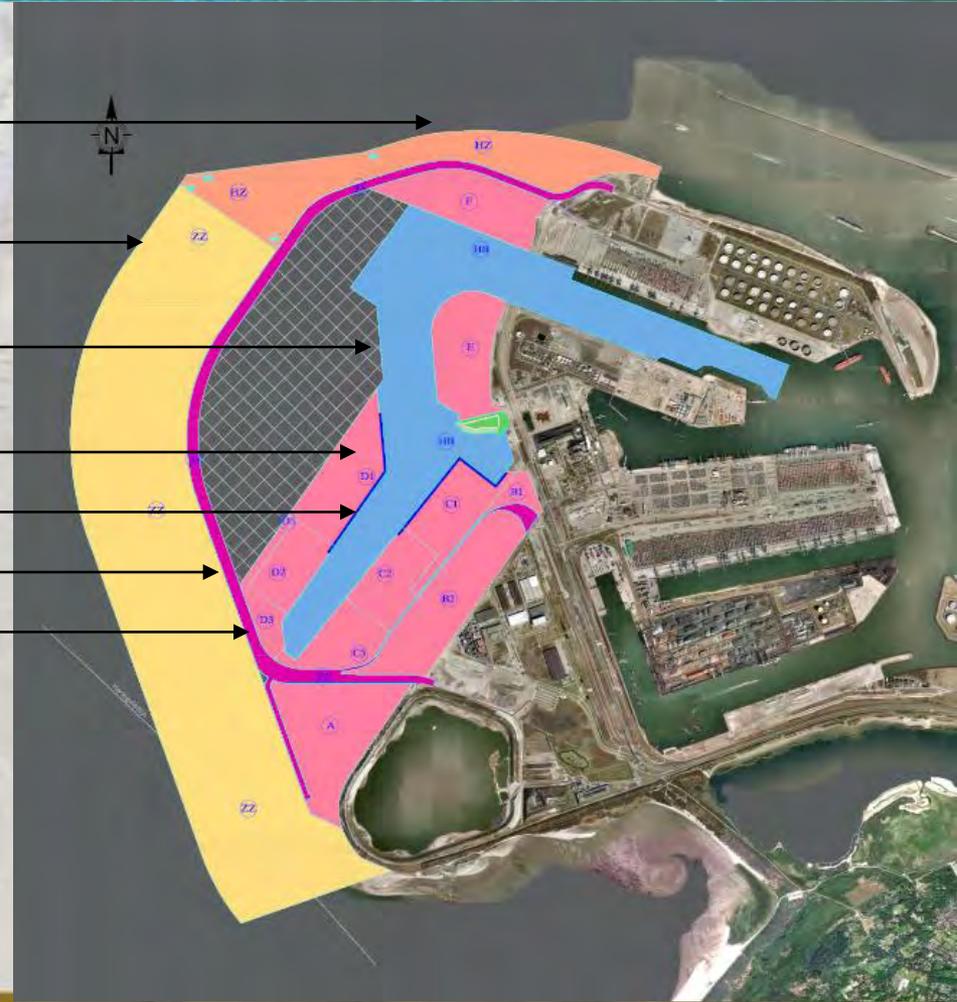
Port Reclamation 700 ha

Quaywalls 3.5 km

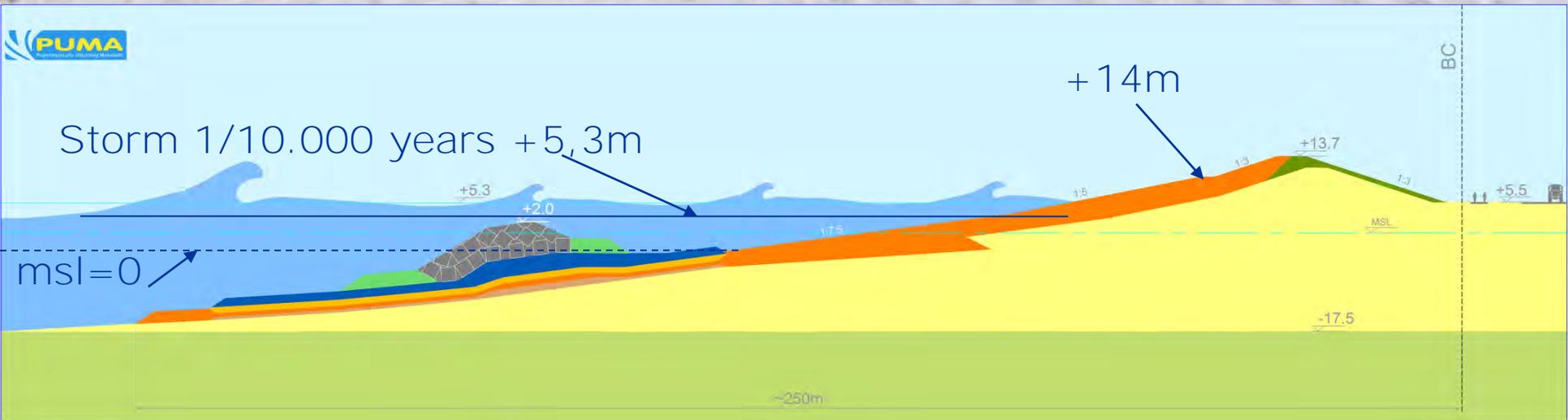
Roads 13 km

Railroads 14 km

- 240 million m<sup>3</sup> sand
- 7 million ton stone
- 20.000 concrete blocks (40T/piece)



# Hard Seawall Defence Total length 3,5 km





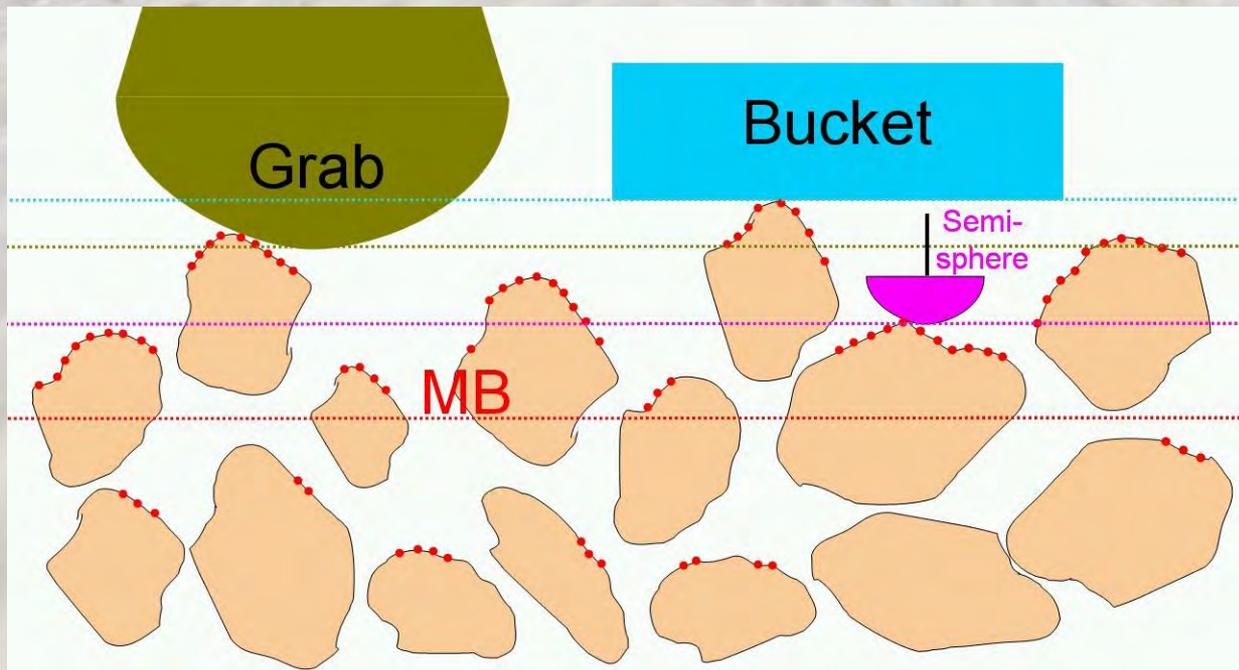
# Rock Works

- Approximately 5.5 million tons of rock from european stone quarries.
- About 1.6 million tons of reuse stone from MV1 block dam.
- 9,558 concrete blocks reused from MV1 block dam



# Measurement methods on rock placement

Understanding the differences in measurements of the average bed elevation between different measurement systems, that can possibly be used on the construction of the Hard Seawall



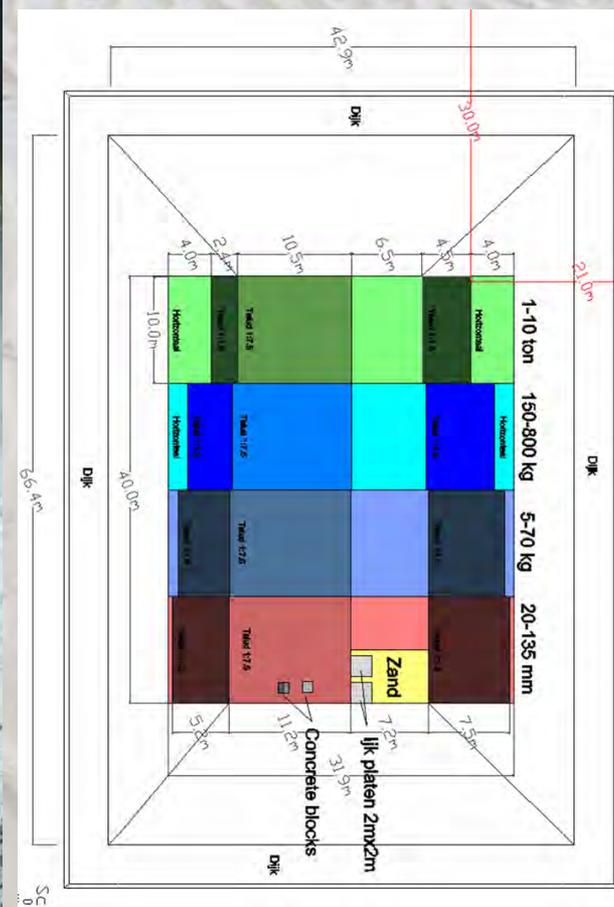
# Test Pit

Comparison of different topographical - and contact measurement methods, acoustic measurement techniques, and laser techniques

- Dry Excavation - Hard Seawall 1:1 scale
- Start construction end of 2009



# Test Pit PUMA 2010 & Verolme dock 1999



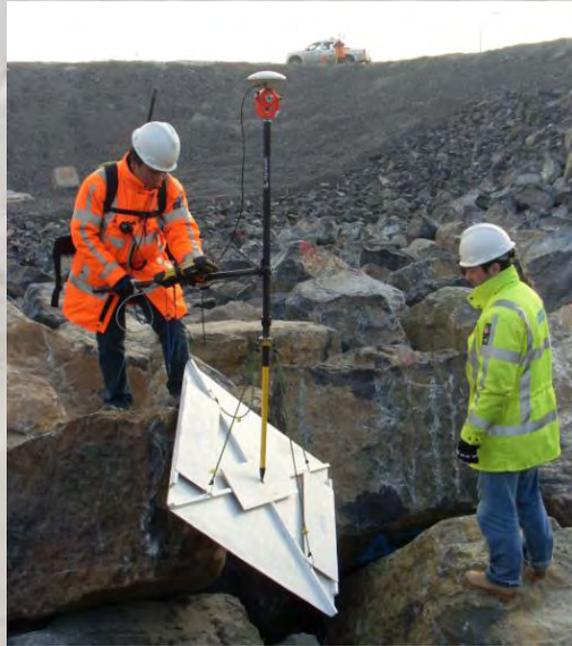
# Test Pit – Dry Measurements

- Semi-spherical measurement
  - Diameter of the half-sphere is equal to the half of the nominal stone diameter.
  - Measurements are carried out in a 1m x 1m grid
- Point measurement



# Test Pit – Dry Measurements

- Plate measurements
  - 1m x 1m tot 150-800kg
  - 2m x 2m voor 1-10 ton



# Test Pit – Dry Measurements

- Grab measurement
- Bucket measurement



# Test Pit – Dry Measurements

- One size bigger!



# Test Pit – Dry Measurements

- Static Laser Scan measurement
- Mobile Laser Scanning measurement
- Fli-map



FUGRO Fli-map



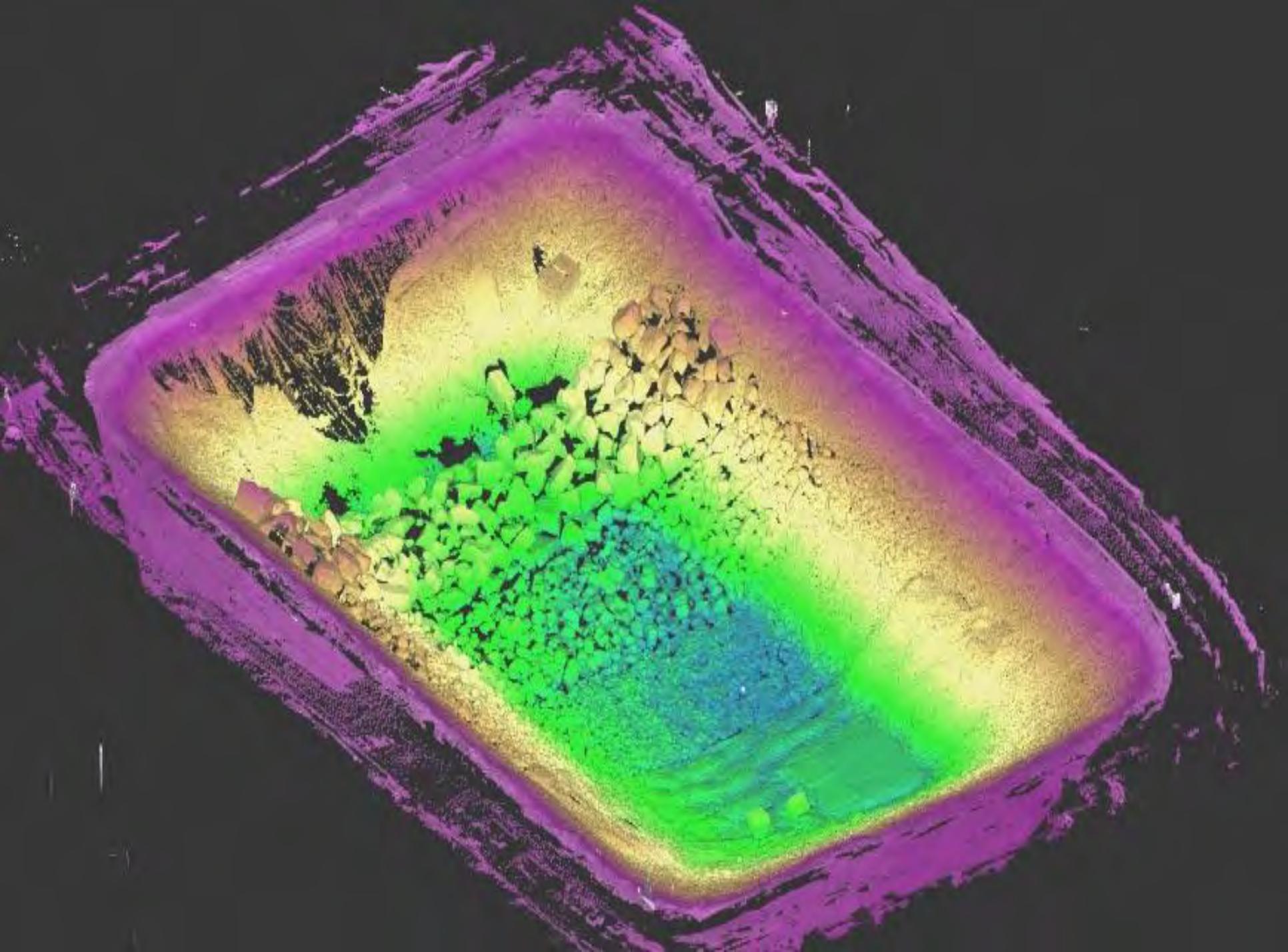
MDL LacerACE



Leica



SICK LMS151



# Test Pit – Underwater Measurements

- Multi-beam Reson Seabat 8125
- Multi-beam Reson Seabat 8101
- Multi-beam R2Sonic 2024
- Multi-beam R2Sonic 2022
- Multi-beam Kongsberg EM3002
- Multi-beam Odom ES3
- Echoscope CodaOctopus-II (375 KHz & 610 KHz)
- Single-beam Reson Navisound 215, 200 KHz met 3° en 9°  $\Delta$



SeaPilot

12-19-YD

BOSKALIS

UASC

Van Noord

# Test Pit – Underwater Measurements

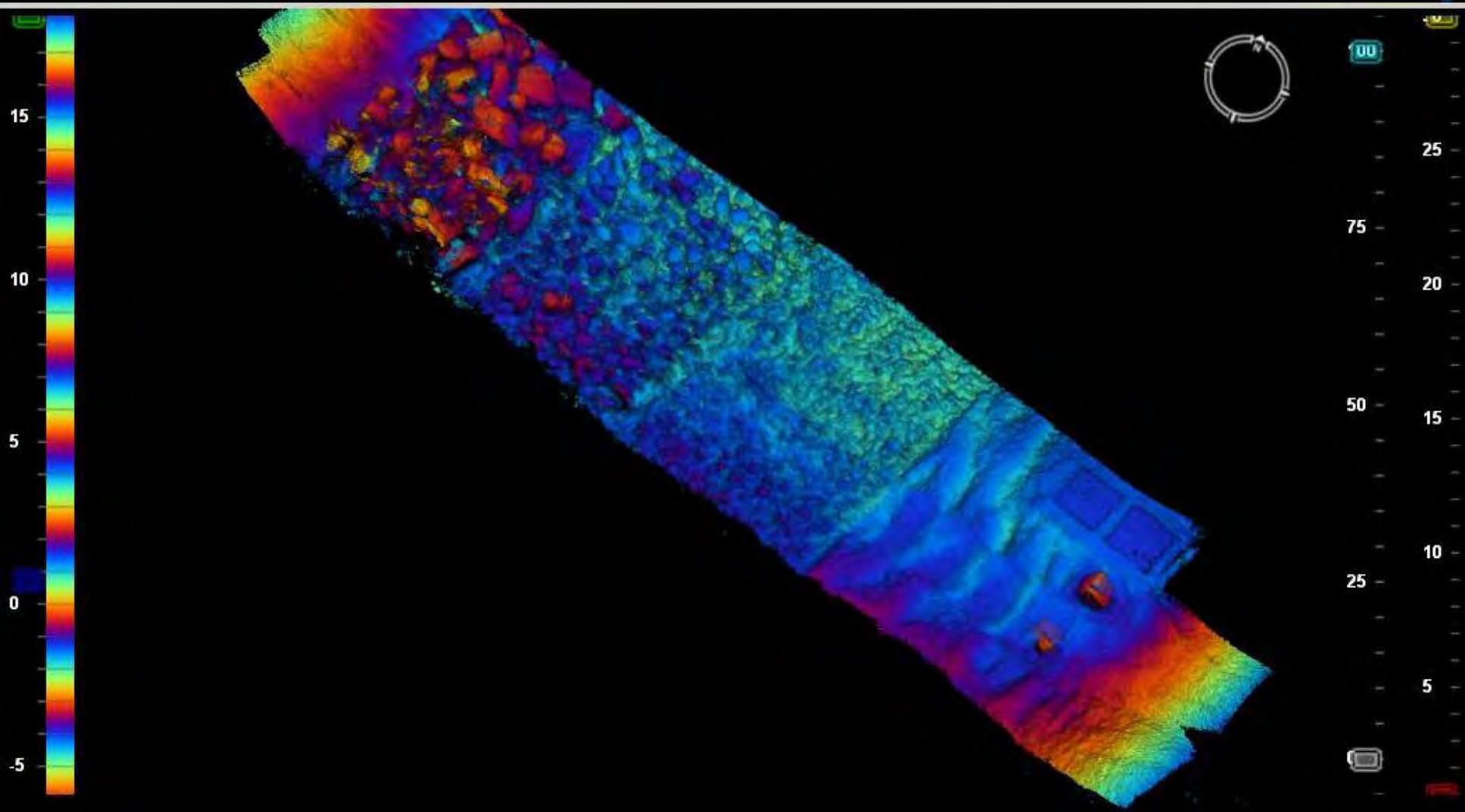
- Setup measurements and Calibration on dry, with different equipment.



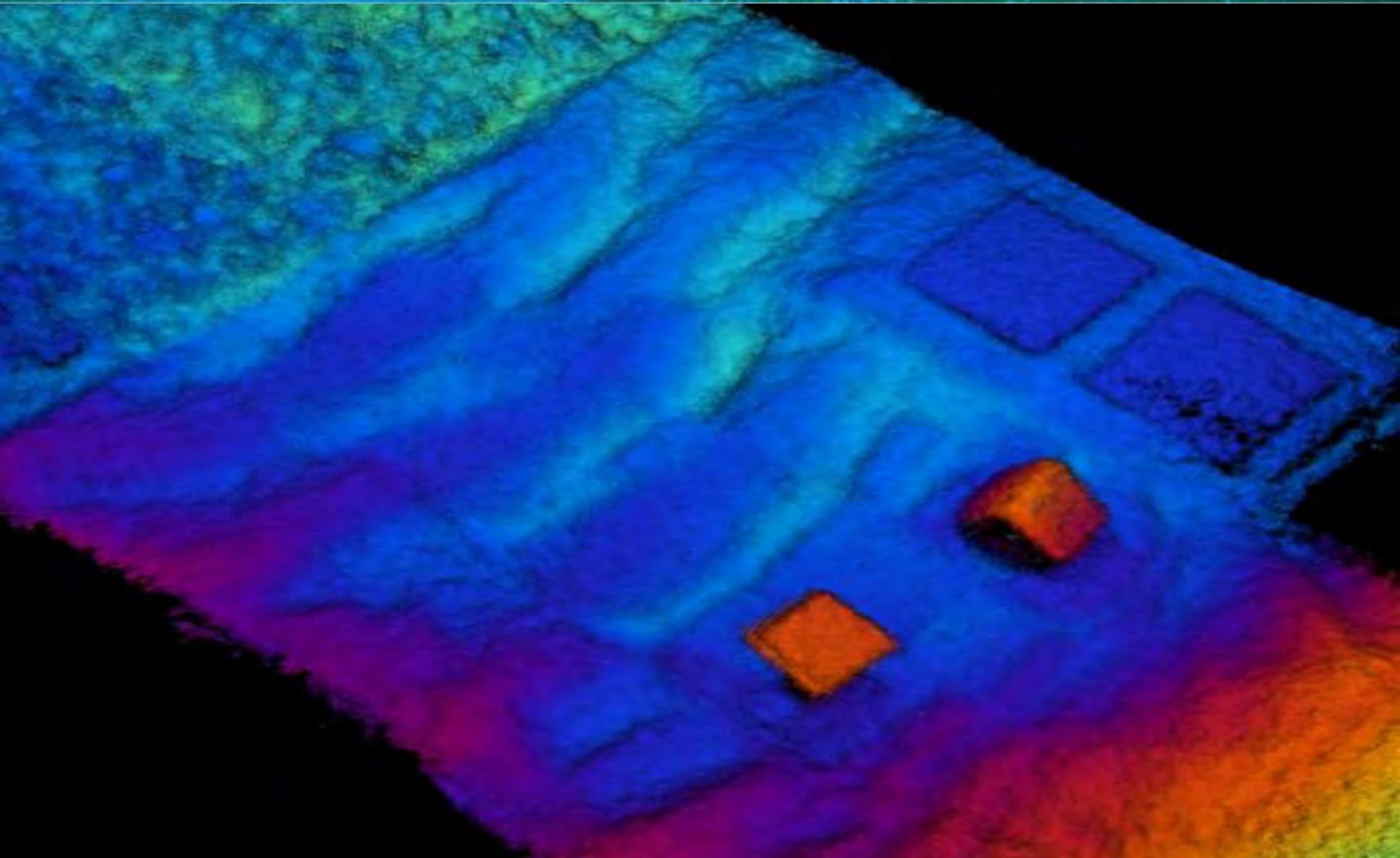
# Test Pit – Echoscope data

www.codaoctopus.com

C:\Users\Tom.Barr\Desktop\PUMA3\PICTURES OF DATA\sd3D16.jpg



# Test Pit – Echoscope data



# Test Pit – Results

Survey System	Sand		20-135 mm		5 - 70 kg		150 - 800 kg		1 - 10 t	
	Systematic Error	Precision								
Total station – plate	n.a.	n.a.	0.07	0.08	0.12	0.09	0.14	0.15	0.11	0.17
Total station – point	n.a.	n.a.	n.a.	n.a.	-0.07	0.07	-0.13	0.19	-0.27	0.51
Excavator – bucket <sup>1</sup>	n.a.	n.a.	0.17	0.13	0.14	0.15	0.34	0.27	0.32	0.40
Excavator - orange peel <sup>2</sup>	n.a.	n.a.	0.17	n.a.	0.08	0.11	0.18	0.21	0.20	0.36
Excavator – sorting	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	0.14	0.22	0.18	0.32
Single-beam	0.01	0.03	0.08	0.08	0.08	0.11	0.09	0.18	0.06	0.26
Multi-beam / Echo-scope	-0.01	0.02	-0.03	0.06	-0.11	0.09	-0.19	0.15	-0.38	0.26
Static laser	-0.01	0.05	-0.01	0.06	-0.04	0.10	-0.05	0.15	-0.18	0.23
Crane based laser	0.02	0.05	0.04	0.07	-0.01	0.10	-0.08	0.15	-0.25	0.24
Fli-map laser	0.00	0.06	-0.06	0.09	-0.12	0.10	-0.17	0.18	-0.36	0.27

# Test Pit – Final Results

Results are included in the new edition of "Make and Measurement Accuracies in the execution of dredging and rock placement" "



# Sand – 240 million m<sup>3</sup> for fase 1



# Construction hard seawall

## Building sand profile



 PUMA aanleg zandkern met sleeplopperzuiger + drijvende leiding + sproeioponton

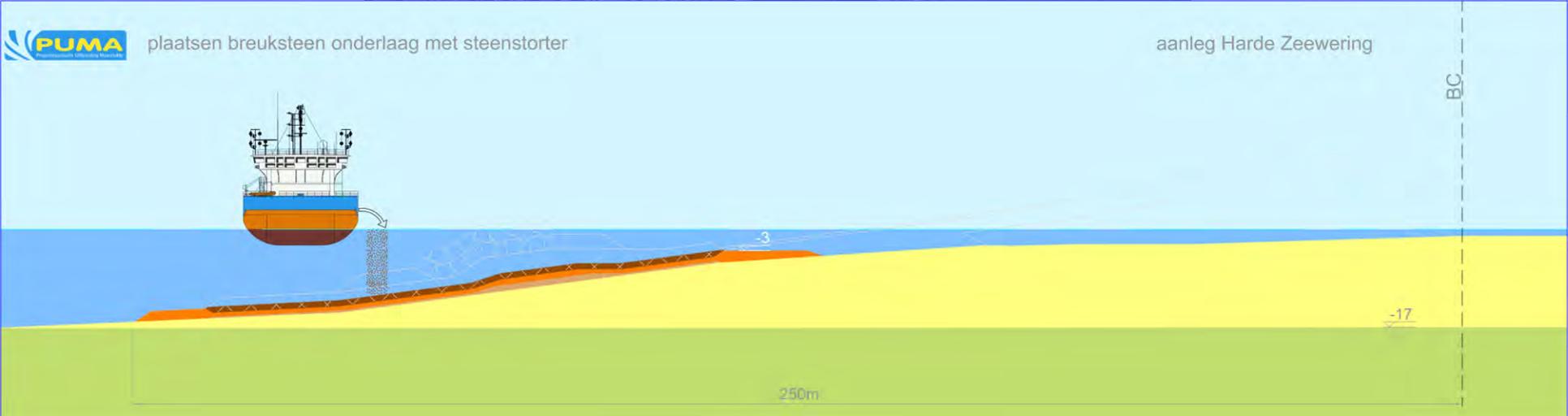
aanleg Harde Zeewering



BC

250m

# Construction hard seawall Rock dumping underwater



# Profiling sand and stone Plough Ship – Arca



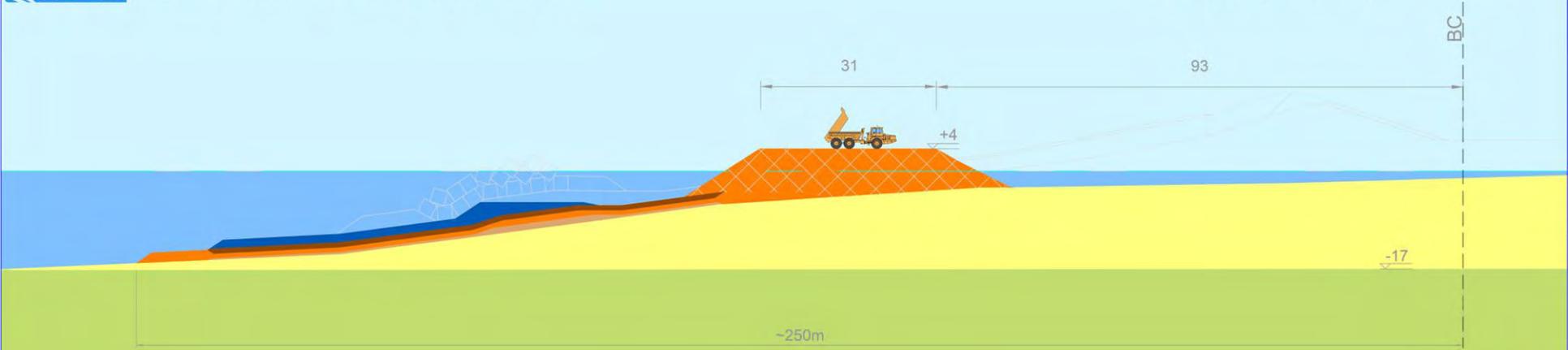
# Construction hard seawall

## Construction temporary work acces



 plaatsen breuksteen werkbaan met dumper trucks

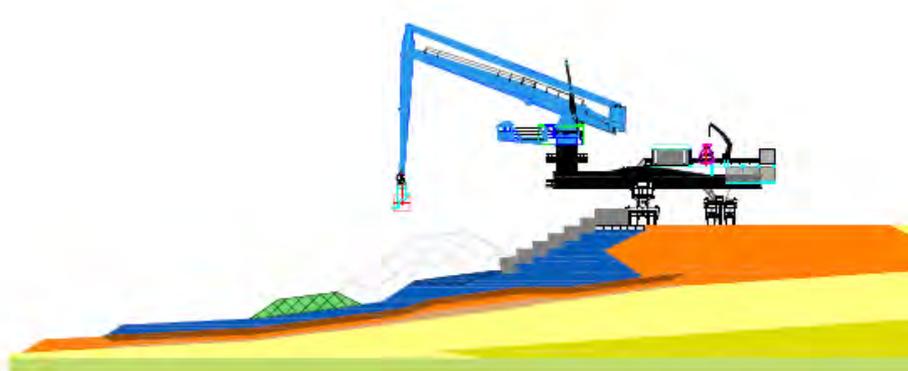
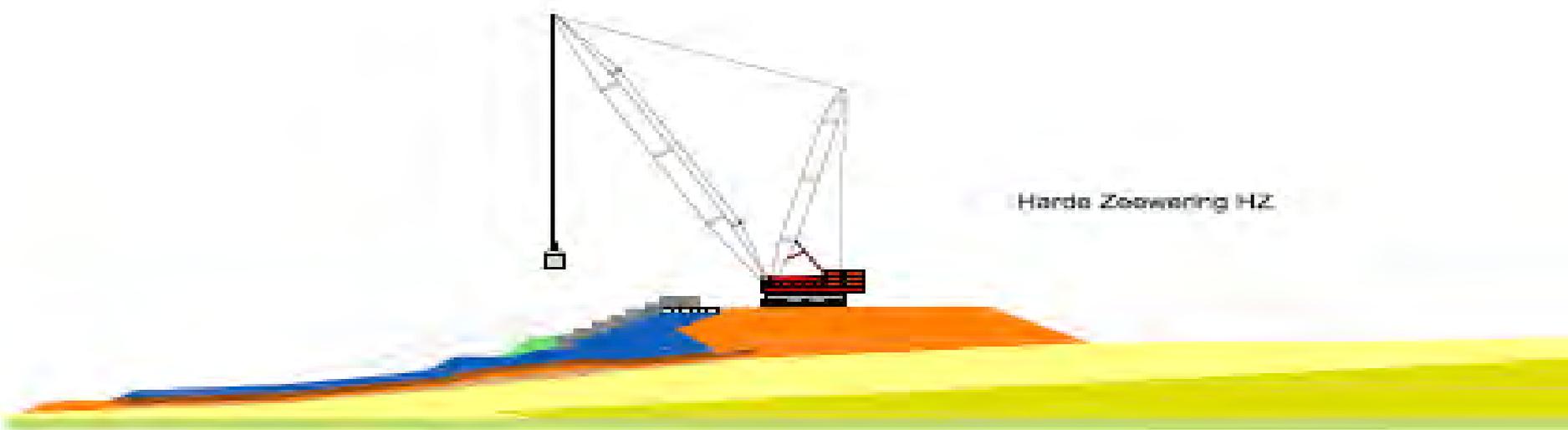
aanleg Harde Zeewering



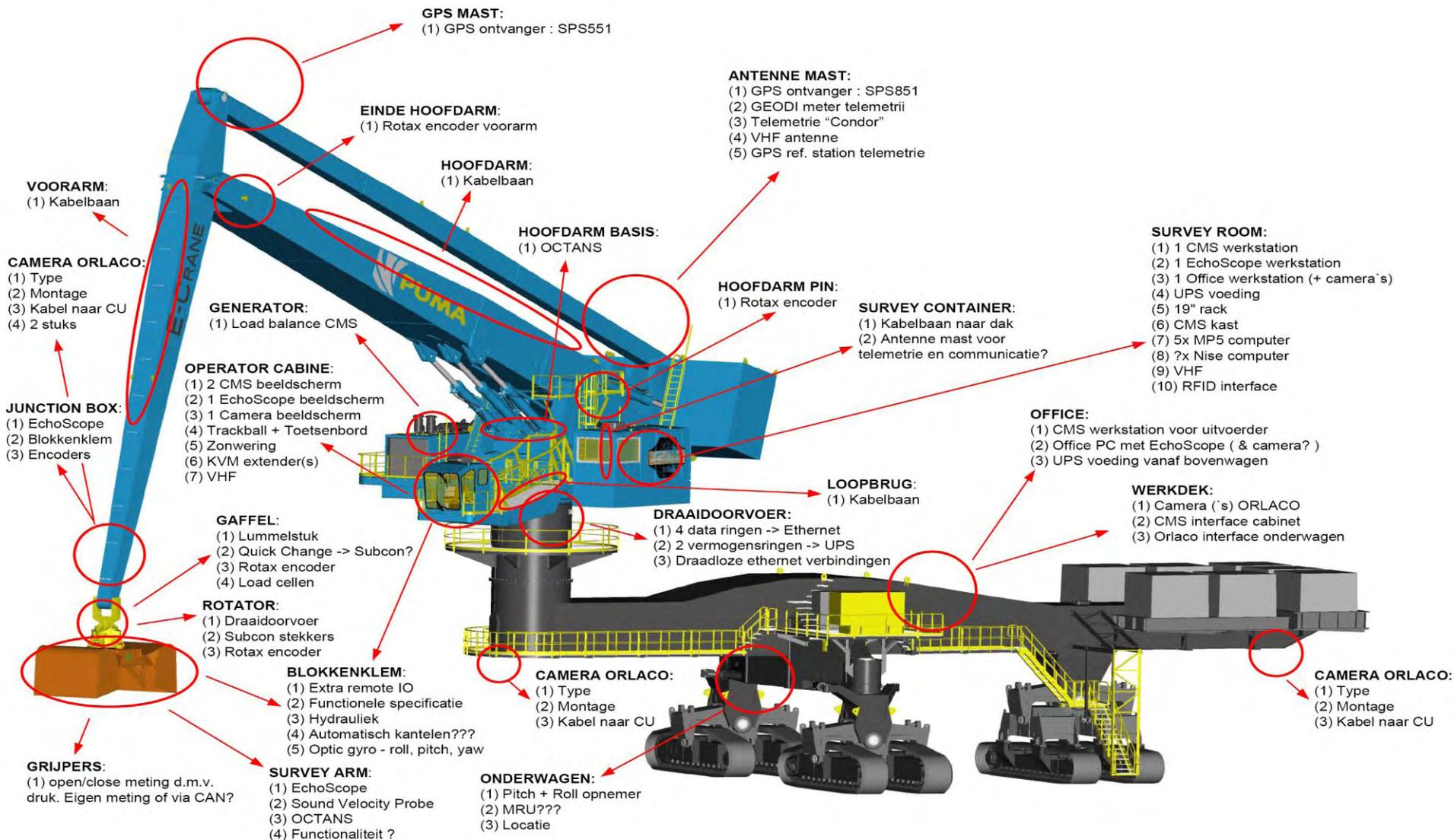
Harde Zeewering HZ



Harde Zeewering HZ



# Blockbuster – Function overview



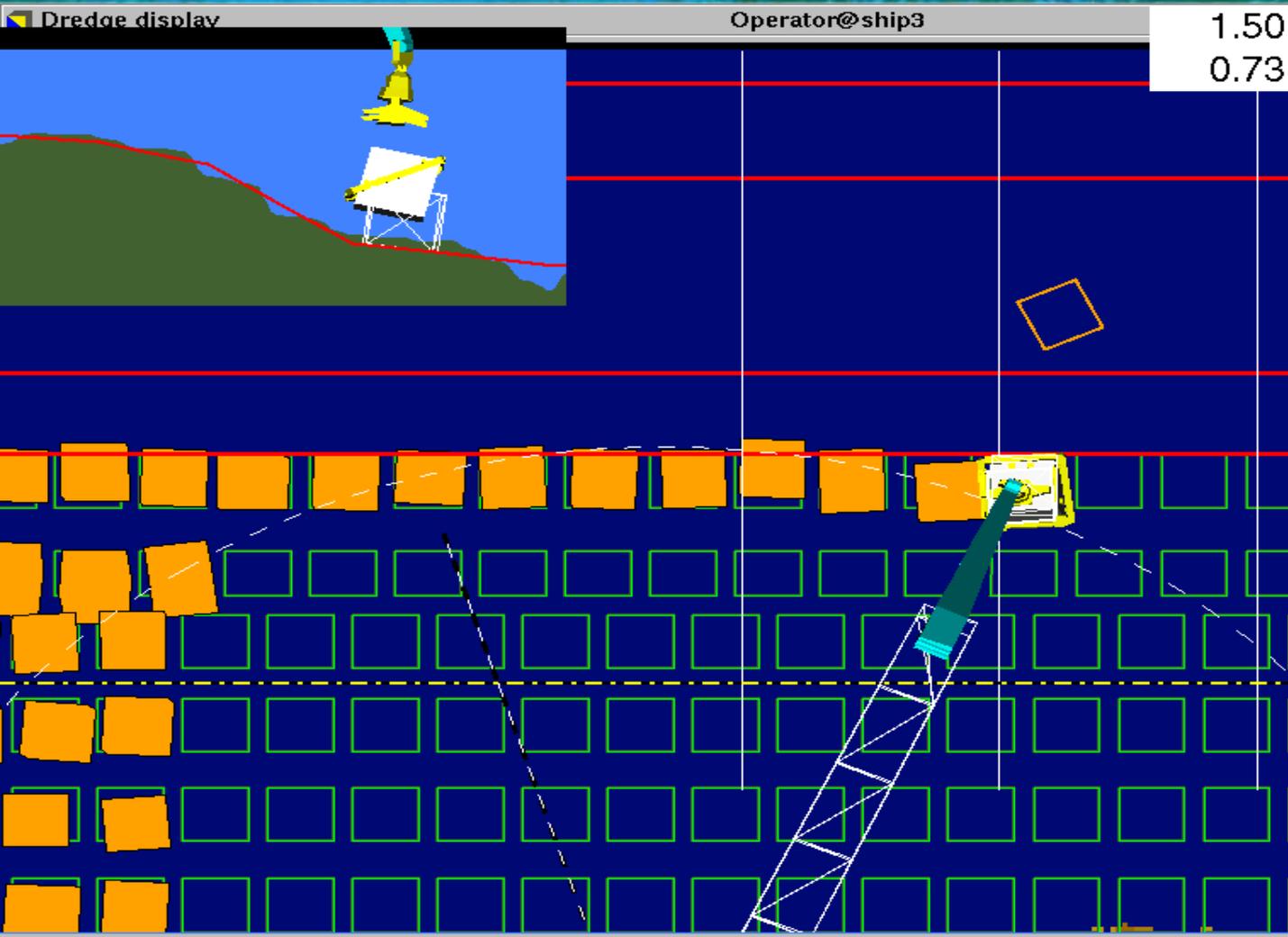


PUMA

BLOCKBUSTER

# Blockbuster Crane Monitor System

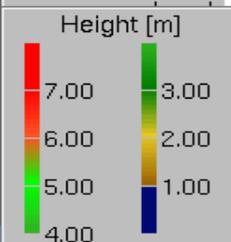
**Dredge display** Operator@ship3 1.50 0.73 16 jun 2011 18:37:06 102



The main display shows a top-down view of a crane's reach area. A grid of green-outlined squares represents the ground. Orange squares represent blocks. A crane arm is shown in the lower right, with a bucket positioned over a block. A red line indicates the crane's current reach. A white box in the upper right corner displays the values 1.50 and 0.73. A vertical white line and a horizontal red line are also visible on the grid.

Block err. slew	0.18
reach	-0.17
height	1.50
roll	6.1
pitch	6.1
heading	-3.7
Bucket depth	6.22
Crane heading	328.5
Crane pitch	0.5
roll	0.7
Crane reach	32.77
Bucket East.	58190.01
North.	444589.80
Bucket height	-6.22
Target block id	00093_01
Bucket Kp	13438.79
Off	8.00

Height [m]



7.00 3.00  
6.00 2.00  
5.00 1.00  
4.00

Block Heading  
Block Tilt  
Block Position

Ready

DISPLAY TOP VIEW SIDE VIEW AFT VIEW SIDE2 VIEW MANUAL INPUT SETTINGS EXTRA PLOT BACK INDEX PRINT SCREEN NIGHT

# Blockbuster position calculation system



# Blockbuster in action



# Blockbuster innovations

- Places blocks of 40 tons at 50m distance
- Horizontal and vertical accuracy  $<0.10\text{m}$
- Crane monitoring system with 3D presentation of blocks
- Gyroscopes that measures the position of the clamp after the placement
- Linking crane monitoring system to PLC for automation purposes
- Automatic calculation of weight to be placed using an integrated grid cell.
- Sensors that monitor the inclination of the chassis
- Direct connection with recording computers for transfer measurement results

# How do we measure this now??

## Objectives:

- Measuring in shallow water to determine layer thickness of the quarry run.
- Measurement of the crown in order to determine altitude.

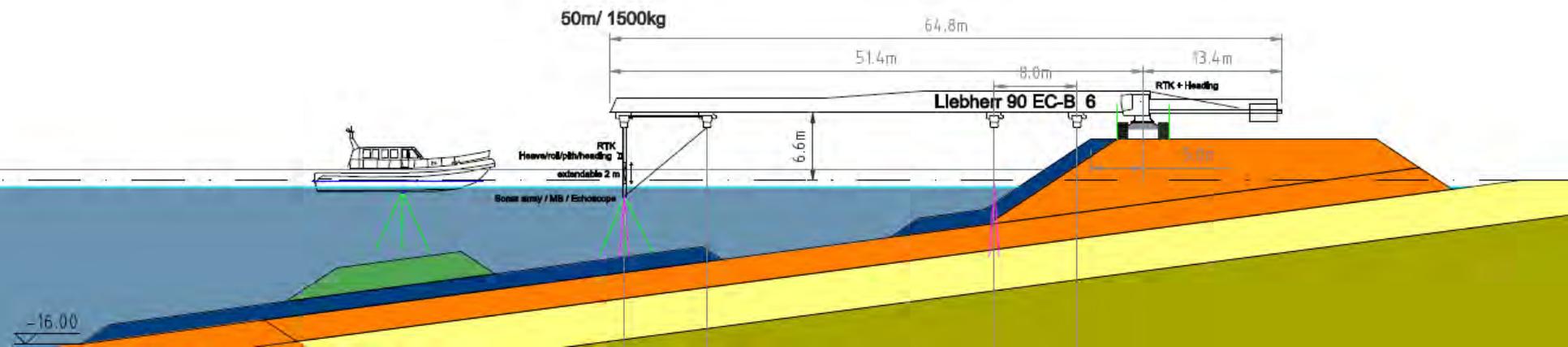
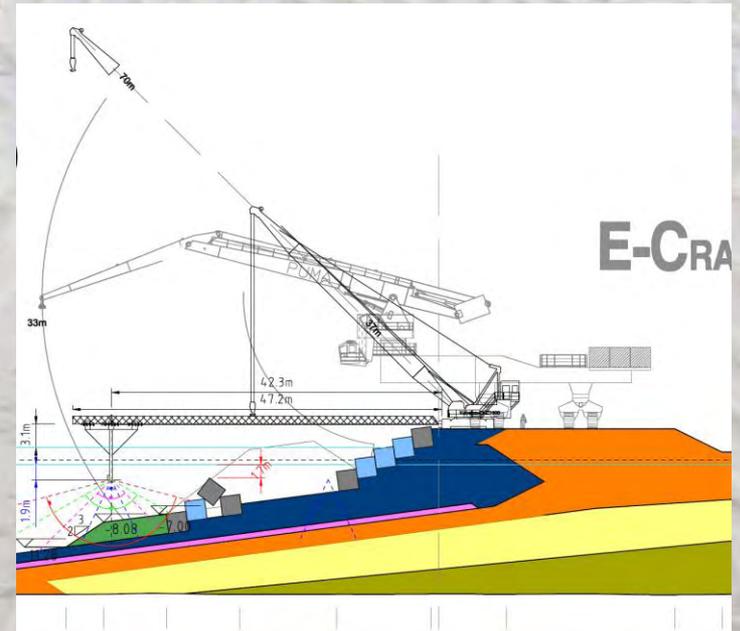
## Which must be taken into account:

- High accuracy
- poor weather conditions

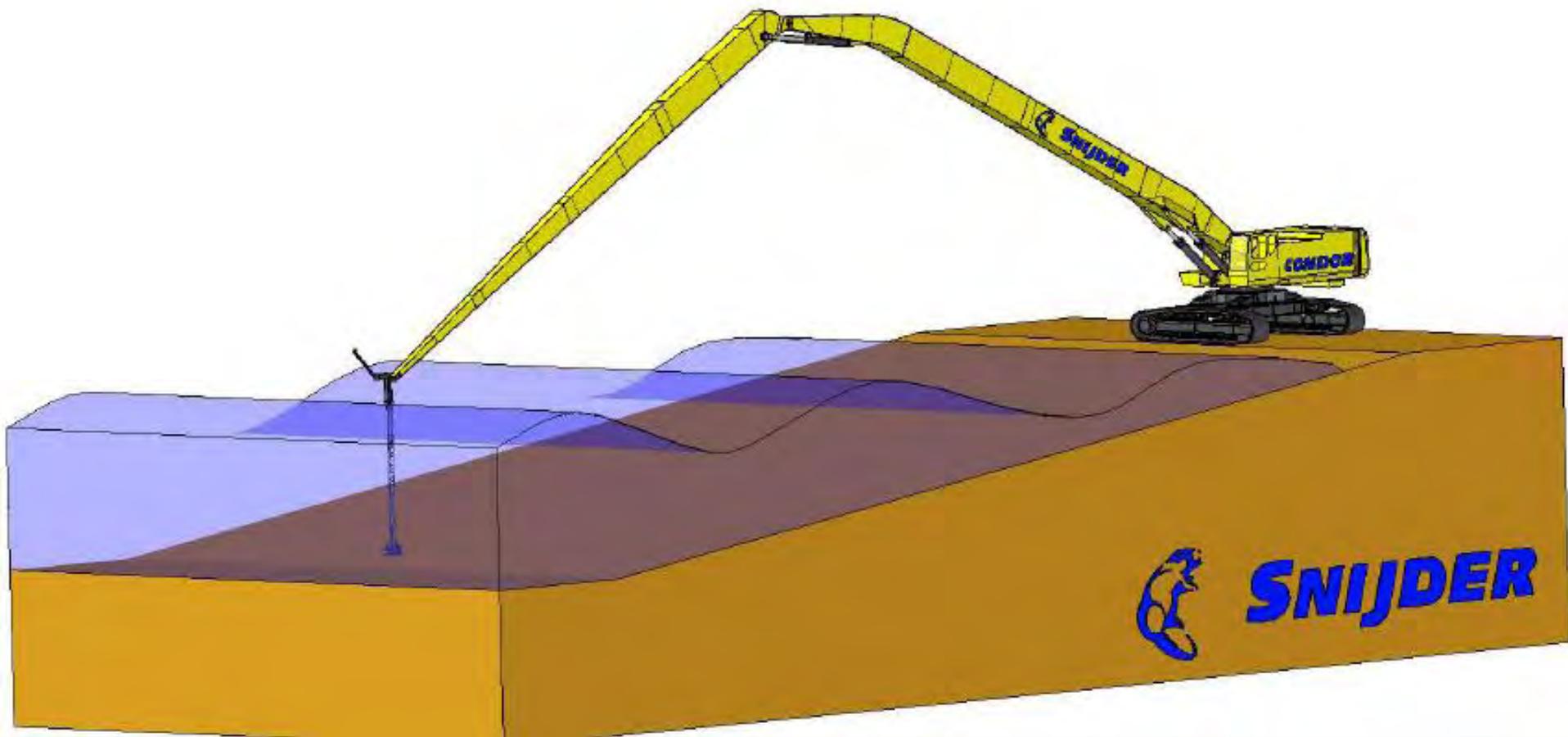
Progress of Blockbuster must be guaranteed!

# With what kind of crane?

- Tower crane
- Crawler crane
- Hydraulic crane
- Telescope crane



# Condor CAT 385, 46.5m



# Condor .... other dimensions ....

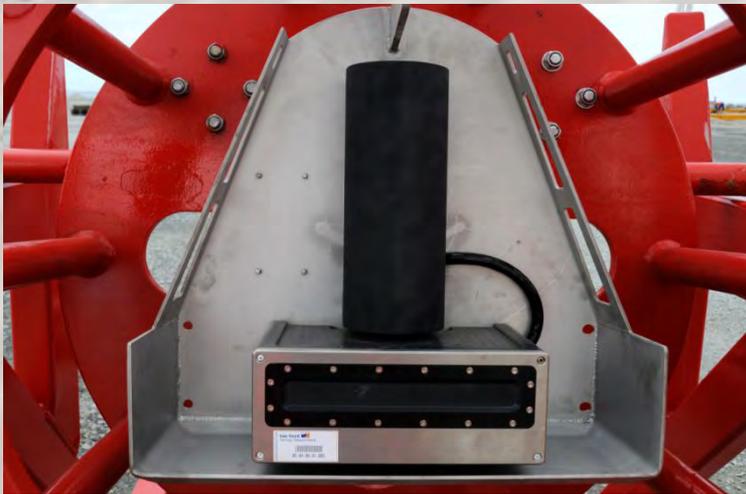




# Condor – no more seasickness



# Condor - Measuring Equipment



# Condor - Measuring



Multibeam survey after the placement of the first 3 blocks.



Multibeam survey on the 1-10 tonne toe structure and the second layer of blocks below the waterline



Laser scan survey of the crest blocks. Additionally the survey vessel will survey the remaining part of the 1-10 tonne toe structure.

# Condor – In action

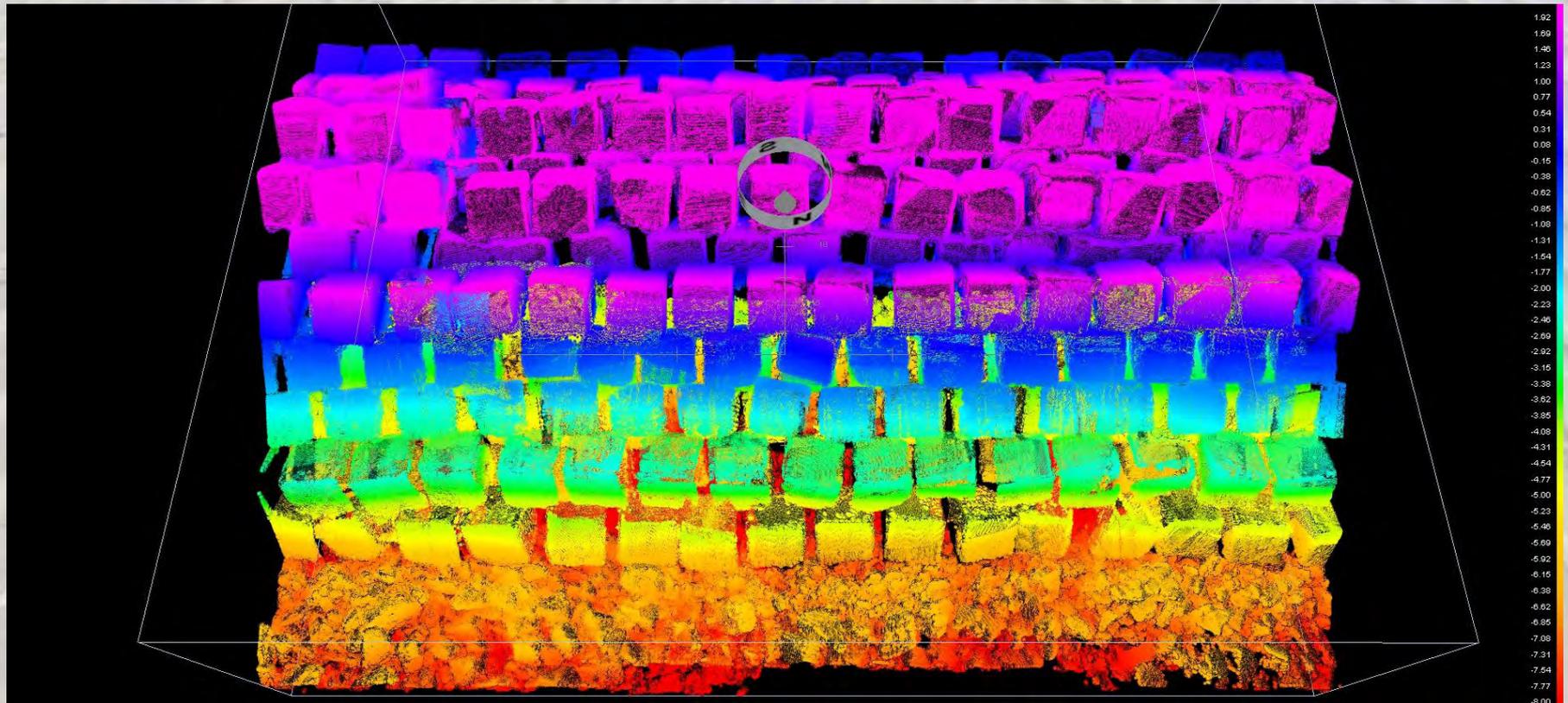


# Condor – Echoscope Data



# Condor - results

Combined survey with Multi-beam and laser scan data





# Condor - innovations

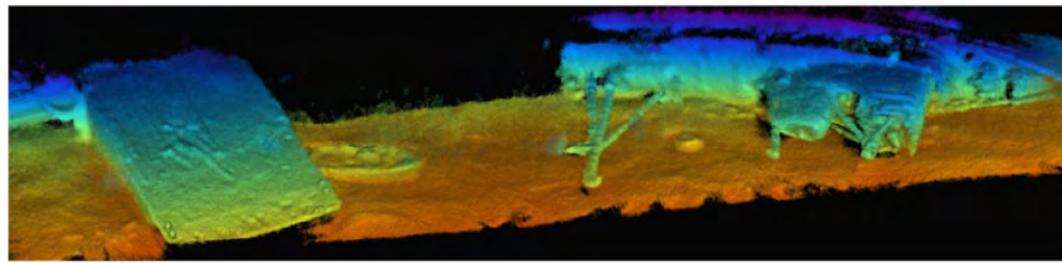
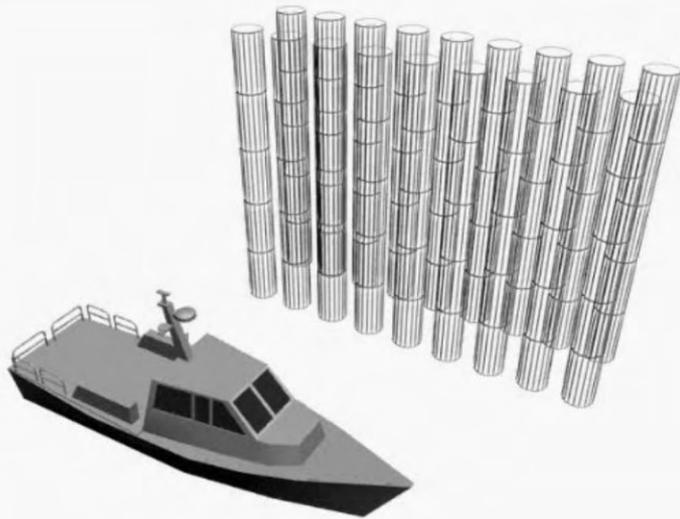
- Unprecedented range of 46.5 m
- Integrated Laser Scan for measuring crown blocks
- Multi-beam measurements to  $\pm H_s$  2m, and 0.5m water depth under the Multi-beam
- High measurement accuracy by mounting all sensors on a single pole
- Camera for visibility



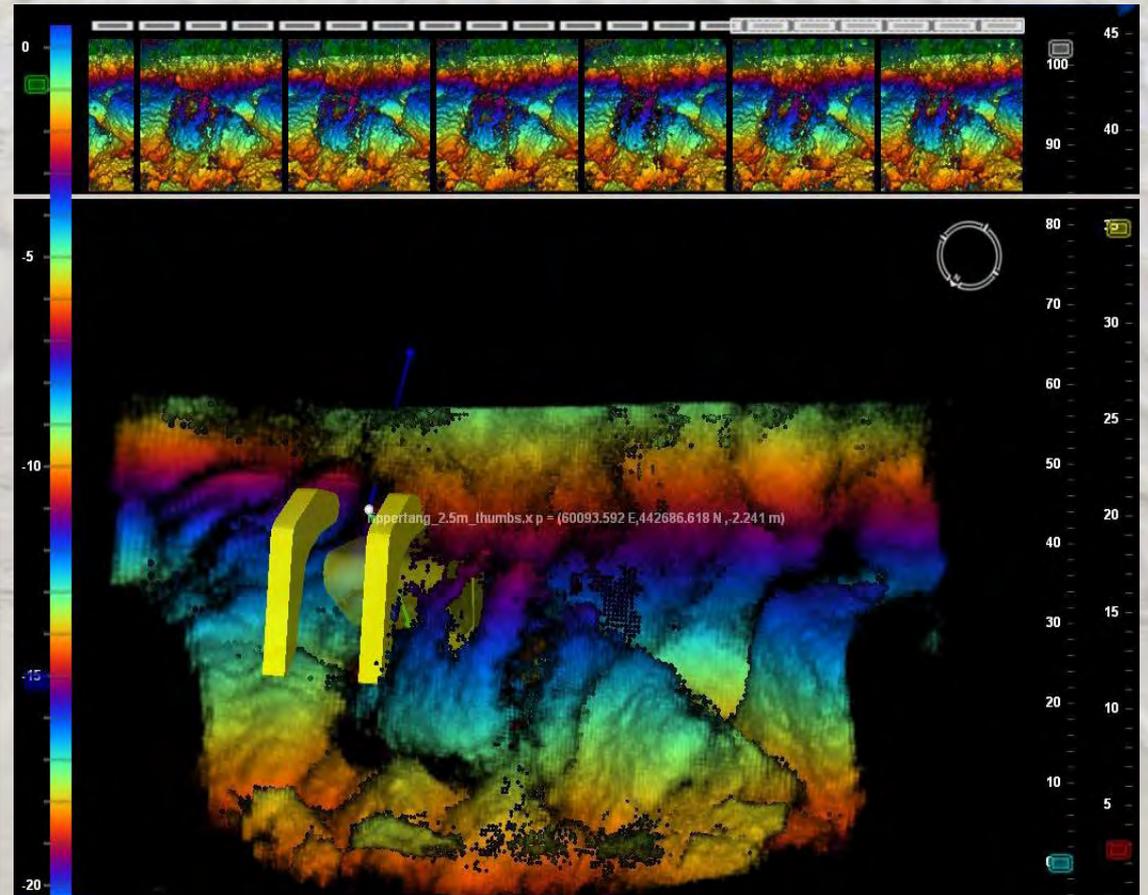
# Removal Concrete Blocks on MV1



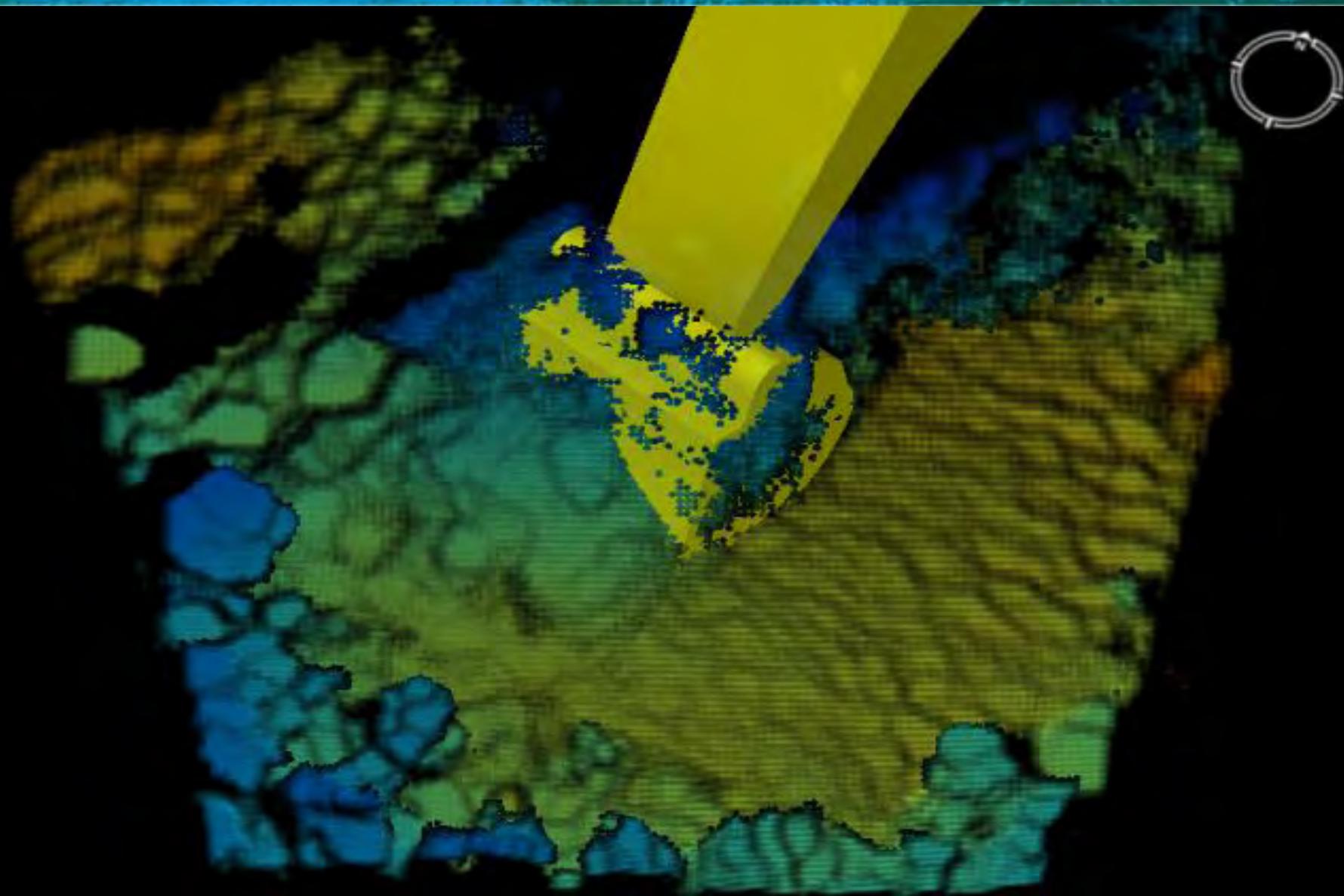
# Echoscope as “underwater camera”



# Echoscope as “underwater camera”



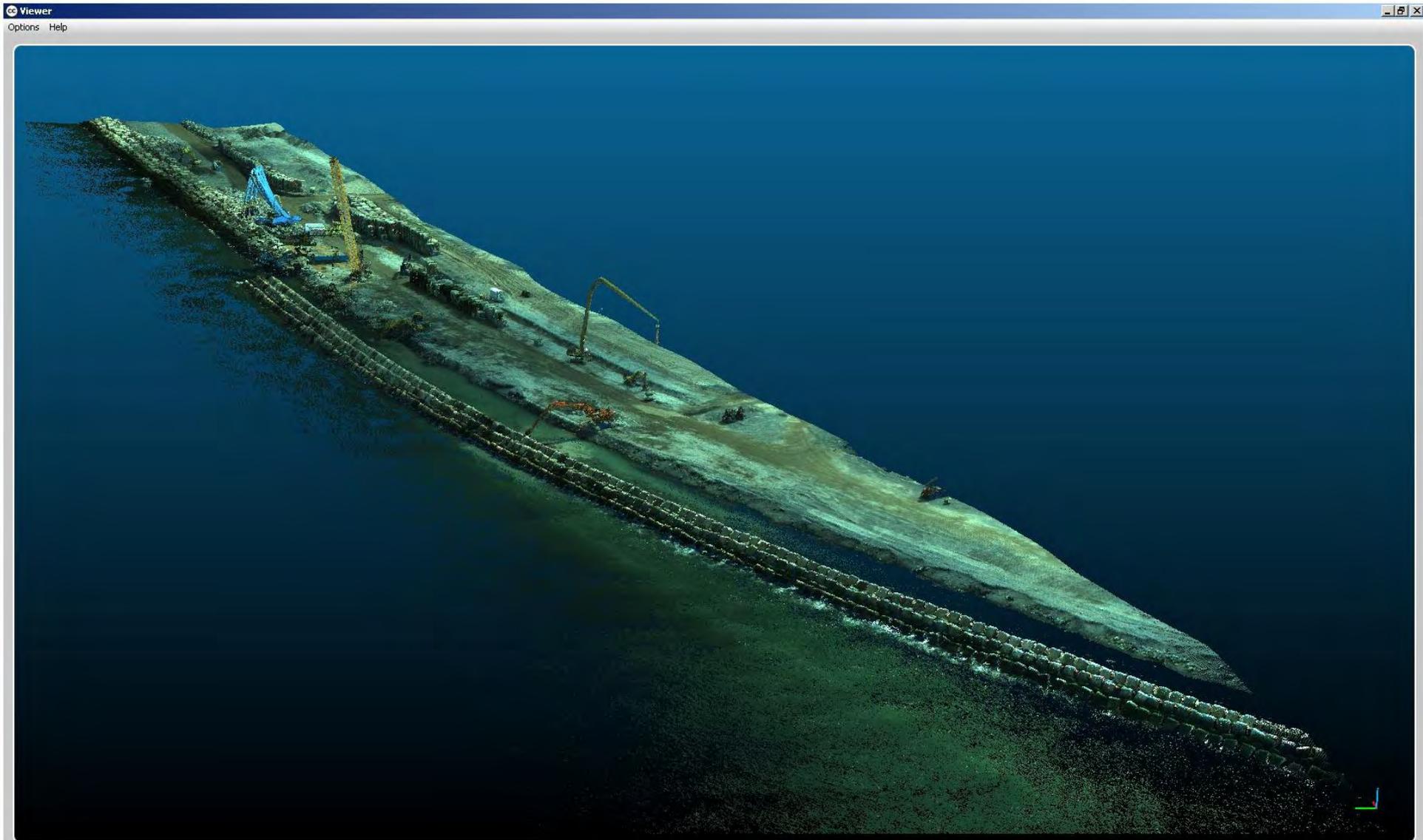
# Echoscope 3D rendering



# Echoscope innovations

- 3D Underwater camera to support the crane operator.
- 3D rendering of the ripper for better interpretation of the scope echo image.
- Ability to load a 3D model as reference layer.
- Automatically tracking the ripper by coupling with crane monitoring system
- Implementation of sound profile readings for accurate measurement
- Using Echo Scope as a survey instrument

# FUGRO Fli-Map



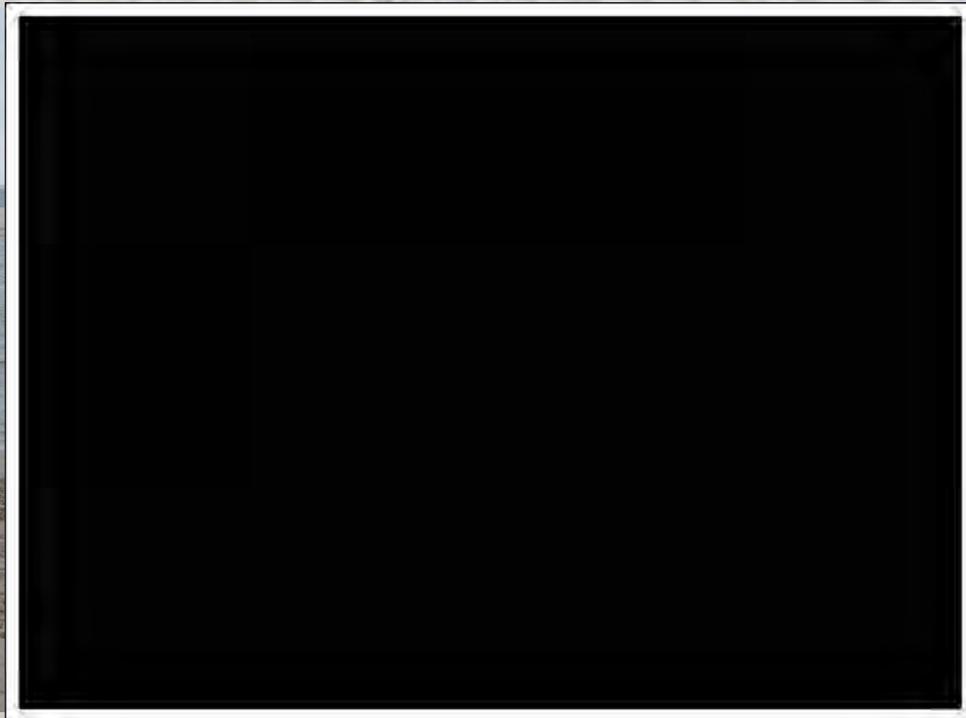
# Alternative : Gatewing X100



# Gatewing X100 Autodesk infrastructure modeler



# Evolution of mobile measurement methods on PUMA



ARGO amphibian

# Evolution of mobile measurement methods on PUMA



Quad Yamaha Grizzly 350 4WD

# Evolution of mobile measurement methods on PUMA

Opps!!....



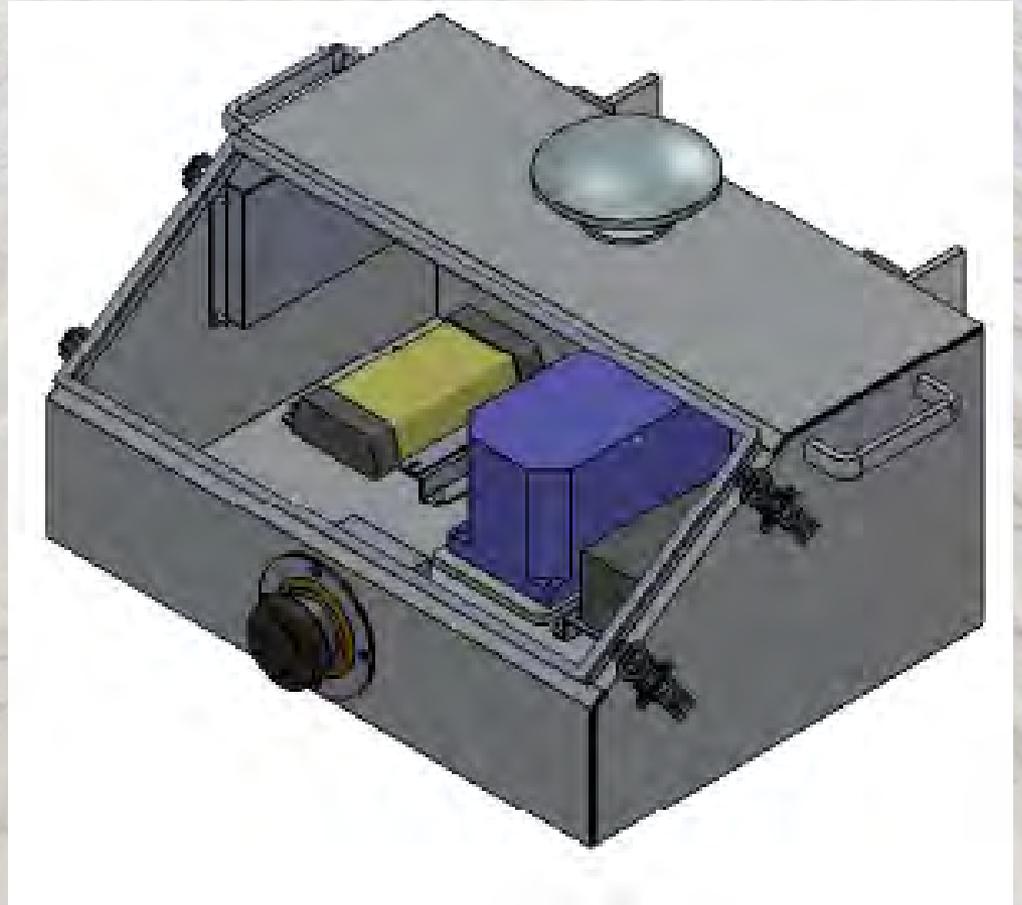
# Evolution of mobile measurement methods on PUMA



# Mobile SICK

- Design

- SICK LMS151
- Trimble SPS851
- Octans IV
- WiFi



# Mobile SICK - innovations

- Cheap (3500,- EURO)
- Small and robust
- Easy interfacing through existing software (PDS2000)
- Quick measurement of large surfaces
- Safe measuring coarse stone gradations
- Measuring stone depots

# Survey Innovations Resume

- The development of a unique Crane Monitoring System (CMS)
- A new feature was added to the Echoscope to present the stick and ripper tool as 3D models
- Survey crane Condor with a massive 46.5 m reach was constructed.
- Recycling the block dam required special use of acoustic viewing systems as underwater cameras.
- Airborne systems like the Gatewing x100 represent a breakthrough which can clearly be applied to future projects.

**Thanks for your attention**

**Waar zee was  
heerst land  
Water verdronken  
in zand**

**Jules Deelder**

**Where there was water  
The land dominates.  
Water sank  
in sand**

**Jules Deelder**

